

CATALOGUE of UAV

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NOTE:

Before looking at the specifications, it is recommended that you read the following CONTENTS at first. It provides you with important advice on UAV model selection.

I. Model Selection Guidance

- Specifications listed in this file are those of UAV PLATEFORM. The UAV platform includes airframe, power subsystem, autopilot, steering engine, and landing gear. Excluding sensors (e.g. gimbals, cameras, etc.) and data-links. But only CL-480S is a exception. CL-480S is a system with "mission payload" that used in reconnaissance.
- 2) If you need an UAV system including sensors, data-link and ground control stations (GCS), please contact the Global sales department of BeST (stands for: Beijing Sagetown Technology Co., Ltd.) for detailed information.
- 3) BeST can provide you with solution (or proposal) to drones application system, such as Transportation system, UAV surveillance system for 2000Km+ range, Forest anti-fire system, Emergency communication system (for live video and data across hundreds of kilometers)
- 4) If no runway available in your project, it is recommended to chose VTOL (Vertically Taking-Off and Landing) composite wing UAV: CL-3, CL-850 or CL-10;
- 5) Feature: If you are going to fly UAV on the plateau (more than 3000 meters above sea level), please select plateau feature for your UAV;
- 6) If maximum range is more than 500 kilometers, please select model CL-4 or CL-850. CL-460 OR CL-480;
- 7) If Electrical fixed wing required, please select model CI-10
- 8) Autopilot has been equipped with all models. So, normal features of autopilot will be default, such as autonomous flight following multiple waypoints (GPS points), etc. Special features like locking and tracking moving object on the ground, "one stroke take-off" and automatic return home and landing in emergency, etc, are also available. You may contact sales of BeST for further information.
- 9) Models adaptive to different environment are available. Models flying on the sea, or flying in low temperature -30 $^\circ$, or in the rain, are available. You are advised to contact BeST.

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- 10) Products are in Industrial category or Military cat.
- 11) Some models of fixed-wing are available with parachutes optionally.
- 12) Feature: All models can be used offshore or inshore. If the UAV is used at sea for a long time, please select "Sea" feature;.
- 13)Large payload tethered multi-motor UAV already released, please check this catalog.
- 14)If no model meets your demand, you are encouraged to contact our salesman. Our R&D team will be glad to provide you with customization service.
- 15) For your information, some data of typical payloads are also provided at the end of this file. In order to avoid misunderstanding, the technical indicators of each model listed in this file are specifications of unmanned aerial vehicle platforms without mission loads or payload.

II. VTOL Composite wing UAV

The Vertical take-off and landing composite wing UAV (VTOL drones for short hereinafter) have fewer requirements on landing field and airspace, could greatly improve the outfield operation efficiency of UAV.

Hybrid power VTOL UAV

The hybrid VTOL Composite fixed wing UAV is gasoline and electric mixed powered, VTOL composite wing UAV. With multi rotor and fixed wing combined, gasoline power and electric force complementary technology, VTOL composite fixed wing UAV erase the three requirement limit, which is runway, environment and good operating skills pilot, realizes fixed wing UAV to vertically take off on battery power, however, fast fly on gasoline power, return hover, and vertically land.

Features:

- ✓ New gasoline-electric hybrid, high speed, far range, long endurance.
- ✓ No need of runway, vertically takeoff and landing.
- ✓ No need of catapult rack
- ✓ Combination of fixed-wing and multi-rotor, high efficiency.
- ✓ One key take off and return home



- √ Easy operate
- ✓ Easy to disassemble, convenient and flexible to use.
- Pure-Electricity powered VTOL UAV

The aircraft adopts modular design, all connection structures are equipped with fast locking, tools not needed for disassemble and assemble process. Electrical and mechanical connections are completed at one time, could be disassembled quickly and easy for transport. The aircraft could achieve full autonomous flight, one button takeoff and landing; Using RTK positioning, takeoff and landing at fixed points, accurate operation.

Features:

- Simple and reliable structure
- No requirements for TOL area and airspace, high efficiency.
- Vertically landing at pre-pointed point precisely
- Fast speed \ long endurance.
- Fully autonomous flight, one button takeoff and landing, simple and safe.

2.1 CL-3 480Km range VTOL UAV



Fig.1 CL-3 Hybrid power Composite wing VTOL UAV

Table 1: Specs of CL-3

Specifications of CL-3

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| Name | Hybrid power Composite wing VTOL UAV | Material | Carbon Fiber |
|--------------------|--|----------------------|-------------------------------|
| Length | 2.3m | Endurance | 5h@5Kg payload |
| wingspan | 3.6m | Navigation | GPS/BDS satellite navigation |
| Height | 0.7m | Curising Speed | 120Km/hr |
| Max Payload | lax Payload 11kg (fule included) | | 480Km+ |
| Max takeoff weight | 45kg | Wind loading | 6 Grade(14m/s) |
| Ceiling | 4500m | Take off /Landing | Vertical Take Off/ Landing |
| Fuel Tank | 7.5L | Operate temperature | -20℃~50℃ |

2.2 CL-850 10Kg 5 hours endurance VTOL UAV



Fig.2 Hybrid power VTOL drones CL-850

Table 3: Specs of CL-850

| Specifications of CL-850 | | | |
|--------------------------|------|-------------------------------------|--------|
| Length | 2.6m | Height (maximum main landing gear) | 0.7m |
| Wingspan | 3.8m | Wing area | 2.5 m² |

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| Landing gear form | Four-point parallel landing gear | Takeoff/landing mode | Vertical Takeoff Vertical landing |
|-----------------------------------|----------------------------------|---|--------------------------------------|
| Maximum speed (sea level) | 140km/h | Cruising speed | 110km/hr |
| Max endurance | 5 hrs | Maximum Altitude for take-off and landing | 2000m |
| payload | 10kg | Max payload | 15kg (2 hours in the air) |
| Wind loading (Positive crosswind) | 6 Grade | Operate Temperature | -20℃~50℃ |
| Max take-off weight | 50kg | Operating humidity | ≤90%RH |

2.3 CL-10 Electricity powered Composite wing VTOL UAV



Fig.3 CL-10 Electrical composite wing VTOL UAV

Table 4: specs of CL-10

| Specifications of CL-10 | | | | |
|-------------------------|-------|-----------------------|--------------------------------|--|
| Wingspan | 2.3m | Max Range | 100km | |
| Length | 1.6m | Altitude in cruising | 1500m(AGL) | |
| Height | 0.7m | Ceiling (ASL) | 2000 m | |
| Conventional payload | 1.2kg | Wind Loading | 5 grade (11m/s) | |
| Max Take-off Weight | 12kg | Horizontal Propulsion | 2xelectric Brushless Motors | |

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| Operate Temperature | -20-50℃ | Endurance | 100minutes |
|--|-----------------------------|------------------|-----------------------------------|
| VTOL Propulsion | 4xelectric Brushless Motors | Take off/Landing | Vertical Takeoff Vertical landing |
| Cruising Speed | 75km/h | Max Speed | 100Km/hr |
| Demonts Of 40 and take off and land automatically and land automatically | | | |

Remark: CL-10 can take-off and land automatically, one key return home or vertically landing.

III. Fixed Wing UAV

3.1 CL-4 Oil Powered 85Kg UAV



Fig4. CL-4 on the Beach, is going to take off

Table 6: Specs of CL-4

| Specifications of CL-4 | | | | |
|------------------------|----------|--------------------|--|--|
| | Length | 3.4m | | |
| Dimension | Wingspan | 4.62m | | |
| | Height | 1.12m | | |
| | Cabin | 920*340*350mm | | |
| Power | Engine | Gasoline engine | | |
| Tank Capacity | | 28L | | |
| Fuel cons | ume rate | 4L/Hr@FULL PAYLOAD | | |



| Weight and | Max Payload | 20kg (fue | I not included) |
|-----------------|---|---|-------------------|
| Load | Max takeoff weight | | 85kg |
| | Cruising Speed | 120km/h | |
| | Max Range | 8 | 300km |
| Performance | Ceiling | 3000m | |
| | Max Endurance | 7 h | |
| Takeoff/Landing | taxiing takeoff, taxiing landing, parachute landing | | parachute landing |
| Control Mode | | onomous control + rei e pre-store or uploadi | · |
| Navigation | | GPS/ BDS satellite n | |
| Maintenance | Engine maintenance cycle time ≥ 150h | | e time ≥ 150h |
| Environment | Temperature | Operating temperature | -20℃~50℃ |
| Environment | Wind Load Rating | 6Grade(12m/s) | |



Fig 5. CL-4 landing on the beach

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3.2 CL-5 9hrs Endurance 800Km range UAV



Fig 6. CL-5 Oil Powered Fixed Wing UAV



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Fig 7. Outlook and Parts of CL-5

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Table 7: Specs of CL-5

| Length | 3.4m | Max Endurance | 9hrs |
|--------------------------|---|--------------------------|---|
| Wingspan | 4m | Power | Gasoline engine |
| Height | 1m | Navigation Mode | GPS |
| Weight of Airframe | 15Kg | Operate temperature | -20℃~50℃ |
| Max loading | 12Kg (fuel included) | Storage temperature | -30℃~60℃ |
| Max payload | 5Kg (fuel not included) | Operating humidity | 95±3% |
| Max Taking Off Weight | 33Kg | Shock resistance | can bear vibration take-off of take-off and landing |
| Max Speed | 130Km/hr | transportation | can be transported by car, air and ship |
| Capacity of Tank | 10L | Parachute | Yes |
| Cruising speed | 130Km/hr | Wind Load Rating | 6 grade |
| Max range | 900Km | Launch Mode | taxiing takeoff, |
| Task radius | 400Km | Landing Mode | taxiing landing, parachute landing |
| Control mode | Autonomous flying, remote manual control, up mentioned modes can switch at any time, flight route prestored or uploading in real time | | |
| Flight Ceiling | 3000m | Engine maintenance cycle | 150Hrs |



CL-9 Plateau UAV



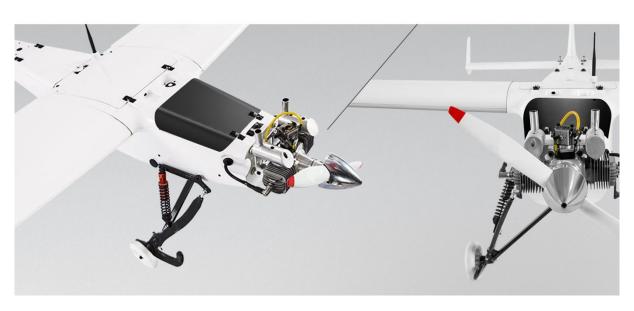


Fig.10 Plateau uav

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Features

- ✓ Takingoff from Plateau high up to 5000m-5500m
- ✓ Max Takingoff Weight: 20kg, Max Payload 3kg;
- ✓ Endurance ≥ 3hrs

Table 9: SPECS OF CL-9

| Length | 2m | Cruising speed | 100-110km/h |
|---|--|---------------------|--|
| Wingspan | 2.7m | Max Speed | 150Km/hr |
| Height | 0.6m | MAX CLIBING RATE | 12m/s |
| Weight of Airframe | 15Kg | Flight Ceiling | ASL5000m |
| Max payload | 3-5Kg (fuel not included) | Max endurance | 4h@payload 3kg |
| Max Taking Off Weight | 17Kg (if runway is good enough, can be 20kg) | engine capacity | 56cc |
| Taxing distance for takingoff and landing | 40-60m | Fule type | 93# above unleaded gasoline + two stroke lubricating oil |
| Speed when takingoff 65km/h | | Operate temperature | -35℃~50℃ |
| Speed when landing | 70km/h | Operating humidity | 5%-95% |

3.4 CL-460 40kg payload oil powered UAV

Features:

- Work normally in severe weather: Cold, hot, snow, and raining
- Work normally in Harsh electromagnetic environment
- 40Kg payload @ 4 hours endurance
- Taking-off on a short runway
- Various usages: can be widely used in field of geophysical prospecting,
 power grid patrol, oil pipeline surveillance, emergency supply

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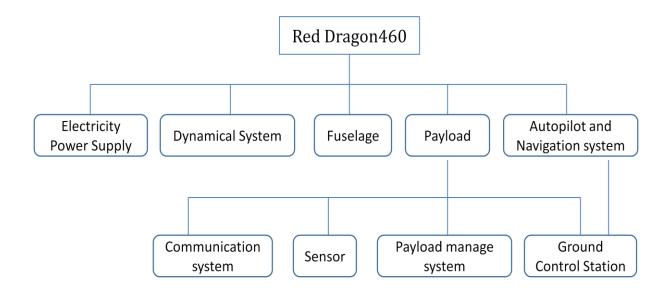


transportation, border patrol, anti-terrorism, reconnaissance and attack

 Within the control range, the ground control system can view live video and control the UAV through data link (Micro Wave or Satellite).



UAV platform includes UAV airframe, navigation system, autopilot, communication equipment, power system and Ground Control Station system.



Specifications of CL-460

Main Technical Parameters of Taxiing Edition (Adjustable according to customer's Requirements)

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| Length | 3300mm | Endurance | 4 hrs |
|-----------------------------|---------------|---------------------------|----------------------------|
| Wingspan | 5940mm | Takeoff/landing mode | Taxiing |
| Ceiling | 6000m | Take-off taxiing distance | <300m |
| Cruising Speed | 120-180 km/hr | Landing taxiing distance | <250m (with Brake system) |
| Propeller size | 32X14 | Engine | Limbach L-275 |
| payload | 40kg | Power | 22HP |
| Meteorological adaptability | | Light Rain, Wind lo | oad rating < Grade 5 |

3.5 CL-480S 70kg payload Reconnaissance Drones

Red Dragon-480S Reconnaissance UAV



Features:

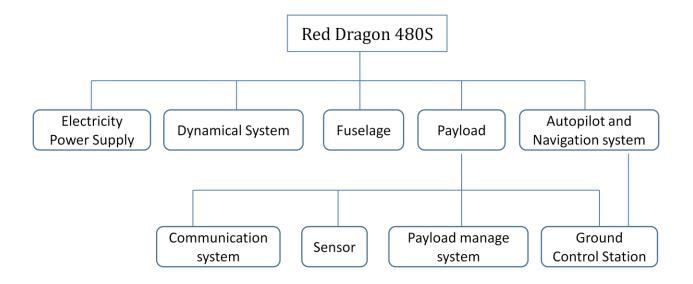
- Work normally in <u>severe</u> <u>weather</u>: Cold, hot, snow, and raining
- Work normally in Harsh electromagnetic environment
- 70Kg payload @ 10 hours endurance
- Taking-off on a short runway
- Landing by parachute in emergency
- Various usages: can be widely used in field of geophysical prospecting, power grid patrol, oil pipeline surveillance, emergency supply transportation, border patrol, anti-terrorism, reconnaissance and attack

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 Within the control range, the ground control system can view live video and control the UAV through data link (Micro Wave or Satellite).

The UAV platform includes UAV airframe, navigation system, autopilot, communication equipment, power system and Ground Control Station system.



1. Specifications of UAV

Main Technical Parameters of Taxiing Edition (Adjustable according to customer's Requirements)

| parameter | value | parameter | value |
|----------------|---------------|---|---|
| Length | 4300mm | Endurance | 10 hrs |
| Wingspan | 8600mm | Takeoff/landing mode | Taxiing, parachute landing in emergency |
| Height | 1600mm | Pneumatic layout | Double vertical tail |
| Ceiling | 7000m | Max Take-off Weight | 390kg |
| Cruising Speed | 140-180 km/hr | Dead Weight | About 180Kg |
| Max Speed | 200 km/hr | Engine | Zanzottera 630 |
| Type of engine | Piston engine | Wind load rating when takingoff and landing | ≤10.8m/s |

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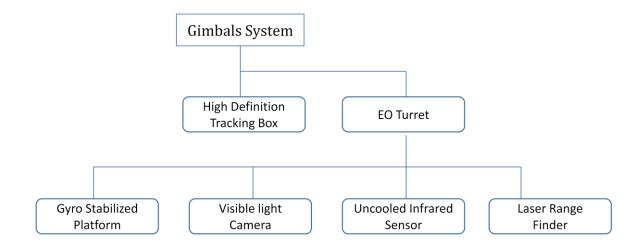


| Payload weight | 70kg | Fuel weight | 120Kg |
|-----------------------------|------|---------------------|----------------------|
| Meteorological adaptability | | Light Rain, Wind lo | oad rating < Grade 5 |

2. Flight Navigation and autopilot System

RedDragon-480 equipped with tactical-level accuracy of the MEMS sensor and differential GPS module, with independent navigation solution function. Using active redundancy structure design, each flight control unit works in standby state. After large data exchange, the authenticity of data and the correctness of calculation are further determined by system self-check and data cross-comparison.

3. Gimbals



(1) Gyro Stabilized Platform

| Search Range (Azimuth) | Nx360 ° |
|---------------------------------------|--|
| Search Range (Pitch) | -120 [∞] +90 (+90 Collection location); |
| Azimuth maximum angular velocity | ≥90°/s |
| Maximum pitch angular velocity | ≥90°/s |
| Azimuth maximum angular acceleration | ≥90°/s² |
| Maximum angular acceleration of pitch | ≥90°/s² |
| Azimuth Stable precision | ≤0.5mrad (1σ) |

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| Pitch Stable precision | ≤0.5mrad (1σ) |
|------------------------|---|
| Azimuth | \leq 50urad (1 σ) (192Hz, 291Hz); |
| Pitch | ≤50urad (1σ) (192Hz, 291Hz); |

(2) Visible light video camera

| Focal length | 4.3mm~129mm |
|--------------------------------------|-------------------|
| ZOOM | Optical zoom 30X |
| Horizontal field of view angle range | 63.7°∼2.3° |
| Working band of light | 0.4~0.9μm |
| type | 1/2.8"colored CCD |
| Image resolution | 1920×1080 |

Taget recognition specs of visible light video sensor

| target | Target size(m) | Detection range(Km) | Recognition distance(Km) |
|---------|-------------------|---------------------|--------------------------|
| people | 0.5×1.8 | 6.8 | 2 |
| vehicle | 3×6 | 15 | 6 |





(3) Long Wave Uncooled Infrared Sensor

| Detector type | vanadium oxide |
|---------------|--|
| Pixel number | 640×512 |
| focal length | 85mm/25mm Optical Dual Field of View |
| Viewing angle | 7.3° (H) ×5.9° (V) /24.6° (H) ×19.8° (V) |





Taget recognition specs of Infrared Sensor

| target | Target size(m) | Detection range(Km) | Recognition distance(Km) |
|---------|----------------|---------------------|--------------------------|
| people | 0.5×1.8 | 2.4 | 0.7 |
| vehicle | 3×6 | 10.6 | 3.5 |

(4) Laser Range Finder

| Working Wavelength | 1.55µm |
|--------------------|---|
| Magazing tanga | 4Km, test condition: target is 2.3m x 4.6m Green Target Plate; in |
| Measuring range | Visibility 8km |

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| Ranging accuracy | ±5m |
|---------------------------|------|
| Repetition frequency | ≤1Hz |
| Accurate measurement rate | ≥95% |

(5) Video Tracker

| RS422 serial port | Baud rate 38400, 8-bit data bit, 1-bit stop bit, no check |
|--|---|
| Tracking algorithm | Built-in target tracking algorithm, combined with intelligent target short-term loss recapture algorithm, achieves stable target tracking |
| OSD | Rich OSD functions to support users to display custom characters, adaptive portal Cross and Tracking Information Display |
| Updating rate of target-to-target center deviation | 30Hz |
| Target-to-target center deviation delay | <15ms |
| Tracking speed | 12 pixels/frame |
| Minimum target contrast | 5% |

(6) Power Supply

| Voltage | DC+24V (20V~25.2V) |
|---------|--|
| Ripple | ≤100mV |
| power | Conventional values: <30W, peak value: <100W |

(7) Environmental adaptability

| working temperature | -40°C∼+60°C |
|---------------------|-------------|
| Storage temperature | -55°C∼+70°C |

IV. Tethered UAV

The tethered UAV is mainly used for long-term uninterrupted air monitoring and emergency communication. It could be equipped with visible light camera and infrared thermal imager, as well as emergency communication relay radio. At present, tethered UAV have been widely used in military, fire control, petroleum, ocean,

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surveying and mapping, transportation, scientific research and other professional fields.

As a communication platform, the tethered UAV taking off with the minimal communication base station, form high altitude emergency communication base station rapidly, it featured with rapid deployment, light and flexible, low landing space requirements, could achieve a fast, reliable, inexpensive broadband communication within the scope of a few tens kilometers, under conditions as sudden natural disasters, communication infrastructure is damaged, bad communication environments, its emergency communication ability has obvious advantage.

As a security platform, the tethered UAV could mounted with dual-light gimbals, high power cameras, high-light lighting systems, monitoring system and other loads to realize high-altitude lighting, aerial fixed-point monitoring and long-distance communication, so as to assure the safety of the venue and person. Among them, the monitoring and reconnaissance system will transmit real-time video and audio data to the ground support command center to eliminate potential risks or conduct in-depth analysis and judgment of data information. In case of accident and hidden danger, the center will predict in advance or acquire the situation in the first time, so to make response strategy and take emergency measures quickly.

Features:

- Long Endurance: 24Hrs Continuous Hovering in the Air
- Heavy Payload: Under hundred meters height, normal payload could reach to 5KG, max.7kg.
- High reliability: Power is supplied by 6 modules, any single block fault will not
 affect other modules, equipped with spare battery, could assure UAV continue to
 fly 6 min. and landing on the safety area on the condition of ground power off.
- High position accuracy: Using differential GPS, could realize accurate positioning
 0.5meters or less
- Easy operation: one button automatic take off and landing or manual take off



4.1 100m Tethered Multi-copter UAV-J6051



Fig.11 Tethered Multi-Rotor UAV-J6051

Table 9: specs of J6051

| Specifications of J6051 | | | |
|-----------------------------|---|--------------------------------|---------------|
| Rotor No. | 6 | 6 Endurance | |
| Wheelbase | 1.3m | Hover Height | 0-100m |
| Net UAV Weight | 9.5kg (Include Power Module) | Take Off/Landing | VOTL |
| 100m Tether Cable Weight | 2kg | Wind load rating 5Grad | |
| Spare Li. Battery Weight | 2.1kg | Operation temperature | -20℃ ~ 50℃ |
| Normal Take Off Weight | 19kg (Include Cable, 100m Height Mission payload 5KG) | Flight Time after Power Off | About 6min |

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4.2 200m Tethered Multi-Rotor UAV-J6052



Fig.12 Tethered Multi-Rotor UAV-J6052

Table 10: specs of J6052

| Specifications of J6052 | | | |
|-----------------------------|---|-----------------------|------------|
| Rotor No. | 6 | Endurance | 8∼24h |
| Wheelbase | 1.3m | Hover Height | 0-200m |
| Net UAV Weight | 9.5kg(Include Power Module) | Take Off/Landing | VTOL |
| 200m Tether Cable Weight | 4kg | Wind load rating | 5Grade |
| Spare Li.Battery Weight | 2.1kg | Operation temperature | -20℃~50℃ |
| Normal Take Off Weight | 21kg (Include Cable, 100m Height Mission payload 5KG) | Power Off Flight Time | About 6min |

4.3 400m Tethered Multi-Rotor UAV-J6154

Table 11: specs of J6054

| Specifications of J6154 | | | |
|-------------------------|-------------------------------|------------------|--------|
| Rotor No. | 6 | Endurance | 8∼24h |
| Wheelbase | 2m | Hover Height | 0-400m |
| Net UAV Weight | 25.5kg (Include Power Module) | Take Off/Landing | VTOL |

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| 400m Tether Cable Weight | 8kg | Wind loading rating | 5Grade |
|----------------------------|--|-----------------------|------------|
| Spare Li.Battery Weight | 4.2kg | Operation temperature | -20℃~50℃ |
| Normal Take Off Weight | 45kg (Include Cable, 400m Height Mission payload 15KG) | Power Off Flight Time | About 6min |

V. Multi copter UAV

5.1 Z4-S: Surveillance Quadcopter



Fig.13 Z4-S

Table12: Specifications of Quadcopter Z4-S

| Wheel base | 1200mm | height | 600mm |
|--------------------------|-----------------|--|-------------------------|
| Dead weight | 7 Kg | Num of motors | 4 |
| motor | Brushless motor | power | lithium polymer battery |
| Material of frame | Carbon fiber | Range of remote control with handheld controller | Not less than 600m |
| Max Taking Off Weight | 12 kg | Max payload | 3kg |

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| Endurance without payload | 25 min | endurance with 2Kg payload | 18~20 min |
|------------------------------|--|-----------------------------|--|
| cruising speed | 3~5m/s | ceiling | 1000m |
| Max speed | 10m/s | CEP precision of Landing | 3m |
| Precision of the flight path | 3m | Wind Load rating | <4 dgree |
| Operating temperature | -10℃~40℃ | camera | HD and/or IR |
| Payload | PAN/TILT camera | Data radio | Transferring bidirectional data, range 5Km |
| Video radio | Transferring one way of live video, range 5Km~10Km | | |

5.2 Z6-S Six Rotor Patrolling Drone

System Features:

- Carbon fiber material, lighter weight and higher strength.
- Disconnectable, Easy to transport and manipulate.
- high performance auto-pilot system to ensure safe flight
- Could carry different task equipments depend on the mission.
- Low voltage alarm function. Could return to base automatically if command signal lost
- check and adjust fly parameters during flight
- Brushless electric motor has advantage of high performance, lower noise and easy to maintain

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Fig.14 Photo of Six-rotor Copter: Z6-S

Table 13: Specifications of 6 rotor copter Z6-S

| Wheel base | 1600mm | height | 900mm |
|------------------------------|-------------------------------------|--|----------------------------------|
| Dead weight | 11Kg | Num of motors | 6 |
| motor | Brushless motor | power | lithium polymer battery |
| Material of frame | Carbon fiber | Range of remote control with handheld controller | Not less than 600m |
| Max Taking Off Weight | 18kg | Max payload | 3kg |
| Endurance without payload | 45 min | endurance with 2Kg payload | 35 min |
| endurance with 3Kg payload | 20 min | cruising speed | 3~5m/s |
| Max speed | 10m/s | ceiling | 1000m |
| Precision of the flight path | 3m | CEP precision of Landing | 3m |
| Operating temperature | -10℃~40℃ | Wind Load rating | <4dgree |
| Payload | PAN/TILT camera | camera | HD and/or IR |
| Video radio | Transferring one way of live video, | Data radio | Transferring bidirectional data, |

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range 5Km~10Km range 5Km



Fig. 15 Z6-S in flying

5.3 Z8-S Eight Rotor Patrol Drone



Fig. 16 Z8-S with PAN/TITLT camera

System Features:

- Carbon fiber material, lighter weight and higher strength.
- Foldable arm, easy to carry and manipulate.
- high performance auto-pilot system to ensure safe flight

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- Could carry different task equipments depend on the mission.
- Low voltage alarm function. Could return to base automatically if command signal lost
- check and adjust fly parameters during flight
- Brushless electric motor has advantage of high performance, lower noise and easy to maintain. It can ensure the drone operating normally in 5 grade wind.

Table 14: Specifications of 8 rotor copter Z8-S

| Specifications of Z8 platform | | | |
|--------------------------------------|------------------------------|---------------------------|-------------------------------|
| Max wheel base | 1360mm | Propeller model | 1861 oar |
| Rack one arm length | 560mm | Propeller weight | 13g |
| rack folding dimension | diameter 1380x high 490mm | Max take off weight | 16Kg (including battery) |
| Rack unfold dimension | Diameter 1700x high 480mm | Max pay load | 10Kg |
| Max power consumption | 4000W | Power battery | 22000MAH*2 lithium battery |
| Motor max power | 660W | Endurance | 25min(@3kg payload) |
| Storage temperature | -20 °C ~ ~65 °C | max rising velocity | 6m / s |
| Maximum Power Current | 30A | automatic cruise speed | 6—10m / s |
| Work temperature | -5 °C ~ +40 °C | wind resistance | 5 grade |
| Material of Propeller and Rack | Carbon fiber | Work limit temperature | -20 °C ~ +55 °C |

| Specs of Payload | | | |
|--|-------------------------------|---|--|
| Item | Technical Index | | |
| | Transmitted power | 200mW (optional) | |
| | Power consumption | Not more than 2W | |
| Specs of Bidirection data Transmission | Transmission distance | ≥10km (LOS condition, bigger Range available on demand) | |
| | Working voltage | 12V | |
| | Operation ambient temperature | -20°C ∼+60°C | |

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| | Weight | Not more than 200g |
|------------------------------|-----------------------|--|
| Ground Control Static | Operation system | Windows XP/Win7 |
| ZT1800GS | Data receive distance | >20km |
| E.L. REBBERGE SCHOOL SERVICE | Power supply | Built-in battery (can external connection) |
| 2 2 10 | Battery endurance | 4Hr |
| Albert School | Internal storage | 4G |
| | Rigid disk | 500G |
| | Weight | About 9kg |





Industrial Grade Surveying and Mapping
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Fig. 17 Z8 is foldable

VI. MAPPING drones

CL-12M Mapping Drones 6.1



Fig.18 CL-12M Mapping Drones

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| Specifications of CL-12M | | | |
|--|-------------------|---|----------------------------------|
| Wingspan | 2.16m | VTOL Propulsion | 4×electric Brushless Motors |
| Length | 1.2m | Horizontal Propulsion | 2×electric Brushless Motors |
| Material of fuselage | EPO+Carbon Fiber | Takingoff and landing | Vertically takingoff and Landing |
| Conventional payload | 0.9kg | Camera for mapping | A7R2 (Brand: SONY) |
| Max Take-off Weight | 8kg | Range covered by wireless communication | 20km |
| Cruising Speed endurance | 15-22m/s 80min | Electricity power | 6s22000mahLi-polimer battery |
| Range | 72~96Km | Service Ceilling | ≤2000m |
| Remark: 6s16000-22000ma, depend on takeoff weight. | | | |

VII.Ground Control Station for UAV



Fig.19 Ground Control Station



Fig.20 Ground Control Station



Fig. 21 Ground Control Station

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7.1 Overview

SageSight1800GS (herein after called as ZT1800GS for short) is matched with any kind of UAV and wireless transmission systems, and it is designed and developed by Beijing Sagetown Technologies Co., Ltd. It features portable and ruggedized design. And it is easy to carry and use. ZT1800GS integrates many functions together, such as flight control, video receiving, telemetry and telecontrol, gimbals telecontrol, flight route programming, one-key-return-home, display and save of video and data, etc.

It has two screens, one for video display featuring short delay, and the other is a touch screen for flight monitoring and programming flight. WINDOWS operation system is pre-installed.

7.2 Features

- Portable suitcase design, easy to transport and operate
- Ruggedized, adaptive to harsh environment, especially rural environment
- High Definition video and Standard Definition video
- Embedded computer
- Live video display and playback
- Multi-functions integrated, such as UAV flight control, live video receiving and display, remote control, tele-control and telemetry, gimbals remote control, flight route planning, "one-button" return hme, display and save of videos, pictures and data.
- Dual-screen design for video display and flight monitoring separately
- Frequency hopping Spread Spectrum technology enhance the anti-jamming ability and wireless transmission stability
- Short latency of video transmission is critical for target locking and tracking by UAV and robot remote control
- Unique control range extending technology, compatible with FUTABA handheld controller, range up to 20km, longer range customizable
- Li-battery pack equipped, endurance more than 2 hours (longer endurance customizable), AC power supply is available
- Received video can be forwarded via WIFI and 4G mobile communication network. Users can watch the video via internet, 4G and WIFI. People around the GCS can watch the videos via cellphone or computer at the same time.



7.3 Block Diagram

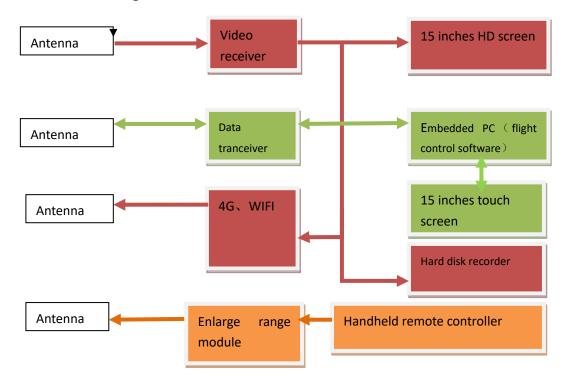


Fig.22. Block diagram of ZT1800GS Ground Station

7.4 Specifications

| | CPU | Intel® 1037U dual-core 1.8GHz processor |
|--------------------|-------------------------|---|
| | CS | Intel® HM76 |
| Embedded Computer | Internal Storage | 2G DDRIII, 8GB at max |
| | Display | Intel® HD2500 video card |
| | Operation System | WINDOW7 |
| B: 1 | Screen Number | 2, one is touching screen |
| Display | Screen Size | 15inch |
| Dhysical Darameter | Dimension | 390mm × 310mm × 100mm |
| Physical Parameter | Weight | about 9kg |
| Electrical | Power Supply | Built-in Li-battery pack 220V alternating current interface |
| Performance | Total Power Consumption | ≤300W |
| Environment | Working Temperature | -20℃ to 60℃ |



| Storage Temperature | -40℃ to 80℃ |
|---------------------|----------------------|
| Humidity | ≤95% (no condensing) |

| Video transmission specs | Operating frequency band | UHF, L, S, C band |
|-----------------------------|--------------------------|---|
| | Quality of video | HD1080p/i , compatible with SD video |
| | sensitivity | -105dBm |
| | Latency of end-to-end | Short latency of SD(120ms) and HD(200ms) video transmission |
| | encryption | AES , 128bit |
| Data transmission specs | Operating frequency band | 902MHz ~ 928MHz, 400MHz, 600MHz, 800MHz |
| | encryption | double, static key; configurable |
| | sensitivity | -108dBm |
| | Air link rate | 19200bps ~ 230400bps |
| 4G | Operating frequency band | Dependent on local 4G service provider |
| | standard | Both FDD-LTE and TD-LTE supported |
| WIFI | protocol | IEEE802.11 b/g/n |

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VIII. Payload of UAV

8.1 Sensor



Fig.23 Sensors of UAV



1. Gimbals



Single light Gimbals



Dual light Gimbals



mini Dual light Gimbals



trilight Gimbals

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2. SAR



SAR

Function and features:

- Miniaturization and low power consumption
- High resolution, live video
- Reliable with actual verification



• Used in fixed wing, multi-copter and Delta wing UAV and manned airplane.

• MiniSAR-5: Channel polarization interference/SAR

 MiniSAR-10E: function, active phased array radar, has the high resolution video, have various mode such as GMTI, MMTI, ISAR and so on.

GMTI mode: Wide-area scanning and target tracking

MMTI mode: Wide-area scanning and single target tracking

ISAR mode: Strip, cluster

3. Mapping camera



Orthogonal Aerial Camera



oblique photograph camera

8.2 Datalink



Video wireless Transmitter



Network bridge



Frequency hopping radio station



Self Organized Network Radio

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Features of Datalink

- Transmission of live video at high definition (1080p)
- Bidirectional data, support telemetry and remote control of UAV
- Cover range up to 20Km, 50Km, 100Km, 150Km, 200Km, etc.
- Extremely Short time delay of video and data transmission, minimum 40ms, world leading level, this feature is necessary for target locking and tracking
- Operating normally in NLOS (Non Line Of Sight) circumstance
- Strong resistance to Multipath interference by the sea
- Support Self Organized Network, without center
- Adaptive to low temperature -40° optionaly